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Total energy of system: $E = T + V$. Kinetic energy: $T = \frac{1}{2} m \dot{\theta}^2 = \frac{1}{2} m l^2 \dot{\theta}^2$ Potential energy: $V = mgy(\theta) = mgl(1 - \cos \theta) = + (1 - \cos \theta) 2 \frac{1}{2} m l 2 \theta 2 mgl \theta dt d dt dE \& = ml 2 \theta \theta \& \& \& + mgl \sin \theta \theta \& = 0$ so, either the system is stationary ($\theta \& = 0$) or:

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$ml\ddot{\theta} = -mg \sin \theta$ - Note:

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General theorems governing differential equations guarantee that if we are given r and \dot{r} at an initial time $t = t_0$, we can integrate equation (1.1) to determine $r(t)$ for all t (as long as F remains finite). This is the goal of classical dynamics. { 2 }

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Classical mechanics - Wikipedia

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